

Basic Group Theory

Def

Def 1 Group.

set $\{G: a, b, \dots\}$ and \cdot form a group iff

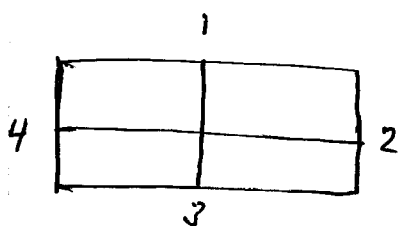
- (a) $a \cdot (b \cdot c) = (a \cdot b) \cdot c$ associative
 (b) $\exists e \in G \Rightarrow a \cdot e = a$ for all $a \in G$
 (c) For each $a \in G \exists a^{-1} \in G \Rightarrow a \cdot a^{-1} = e$

Examples: $C_2 = \{e, a, a^2 = e\}$ Cyclic groups

$$C_3 = \{e, a, a^2, a^3 = e\}$$

DefAbelian \Leftrightarrow commutative i.e. $a \cdot b = b \cdot a \quad \forall a, b \in G$ Deforder = number of elements.

Simplest non-cyclic group is of order 4

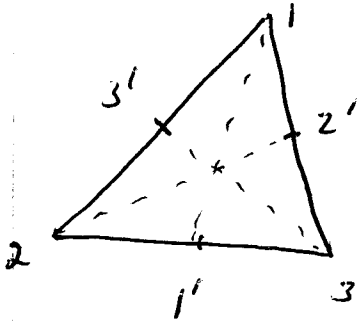
 D_2 Dihedral Group $\{e, a, b, c\}$ 

	e	a	b	c
e	e	a	b	c
a	a	e	c	b
b	b	c	e	a
c	c	b	a	e

Two reflections (13) and (24) and a rotation by π .

(2.2)

Smallest non-abelian group D_3



$(11')$ $(22')$ $(33')$ reflections
 rotations by $2\pi/3, 4\pi/3$

Def: Subgroup subset $H \in G$ which forms a group under the same multiplication law

e.g. $D_2 \ni \{e, a\}$ ← subgroups each is isomorphic to C_2
 $\{e, b\}$ ✓
 $\{e, c\}$ ✓

Rearrangement Lemma

if $p, b, c \in G$ and $pb = pc \Rightarrow b = c$

so

if b, c are distinct so are pb and pc .

then multiplication by an element of G against all of G just rearranges the group elements

$$\{g_1, \dots, g_n\} = G \quad pG = \{g_{p_1}, \dots, g_{p_n}\}$$

$P = \begin{pmatrix} 1 & 2 & 3 & \dots & n \\ p_1 & p_2 & p_3 & \dots & p_n \end{pmatrix}$ ← set of permutations
 S_n ← symmetric or permutation group.

(2.3)

Def:Isomorphism: G isomorphic to G' iff

\exists a one-to-one mapping between them that preserves the multiplication rule.

$g_i \in G$, $g'_i \in G'$ and $g_1 g_2 = g_3 \Rightarrow g'_1 g'_2 = g'_3$
and so on

Thm (Cayley)

Every group G of order n is isomorphic to a subgroup of S_n .

Pf: Rearrangement lemma $a \in G \rightarrow P_a = \begin{pmatrix} 1 & 2 & \dots & n \\ a_1 & a_2 & & a_n \end{pmatrix} \in S_n$

where $g_{a_i} = a g_i$ $i=1, \dots, n$

say $ab = c$ then

$$\begin{aligned} P_a P_b &= \begin{pmatrix} 1 & 2 & \dots & n \\ a_1 & a_2 & & a_n \end{pmatrix} \begin{pmatrix} 1 & 2 & \dots & n \\ b_1 & b_2 & & b_n \end{pmatrix} \\ &= \begin{pmatrix} b_1 & \dots & b_n \\ a_1 & & a_n \end{pmatrix} \begin{pmatrix} 1 & \dots & n \\ b_1 & & b_n \end{pmatrix} = \begin{pmatrix} 1 & \dots & n \\ a_{b_1} & & a_{b_n} \end{pmatrix} \end{aligned}$$

but $g_{a_{b_i}} = a g_{b_i} = ab g_i = c g_i$

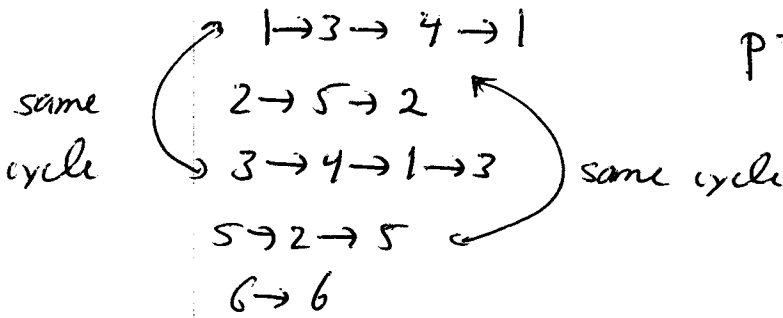
so $P_c = \begin{pmatrix} 1 & \dots & n \\ a_{b_1} & & a_{b_n} \end{pmatrix}$ as well.

(2.4)

Example: $C_3 = \{e, a, a^2, a^3=e\}$

cycle notation $P = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 \\ 3 & 5 & 4 & 1 & 2 & 6 \end{pmatrix}$

$$P = (134)(25)(6)$$



$$\begin{aligned}
 e \cdot C_3 &\rightarrow e && (123) && \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} \\
 a \cdot C_3 &\rightarrow \{a, a^2, e\} && \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} && \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} \\
 a^2 \cdot C_3 &\rightarrow \{a^2, e, a\} && \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix} && \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix}
 \end{aligned}$$

$\therefore C_3 \cong \{e, (123), (321)\}$

Classes and Invariant Subgroups

Def: Conjugate elements $a, b \in G$ are conjugate if $\exists p \in G \ni b = pap^{-1} \iff b \sim a$

Example in S_3 $(12) \sim (31)$ because

$$(23)(12)(23)^{-1} = (31) \quad \text{check.} \quad \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix}$$

Def:

Conjugate class : set of group elements that are conjugate to each other. (2.5)

e.g. S_3 has three conjugate classes

$$\mathcal{C}_1 = \{e\}$$

$$\mathcal{C}_2 = \{(12), (23), (13)\}$$

$$\mathcal{C}_3 = \{(123), (321)\}$$

Why gpg^{-1} just relabels the cycle p_i w g_i .
see

$$(23)(12)(23)^{-1} =$$

$$\begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix} = (13)$$

so $(12) \sim (13) \iff$ These are conjugate.

Def:

Conjugate subgroup : If H is a subgroup of G and $a \in G$

Then $H' = \{aha^{-1}; h \in H\}$ forms a subgroup of G and is a conjugate subgroup.

either $H \cong H'$ (isomorphic) or only have e in common.

Def:

Invariant Subgroup $H \subset G$ is an invariant subgroup if it is identical to all its conjugate subgroups.

Example: $C_4 = \{e, a, a^2, a^3, a^4=e\}$

$H = \{e, a^2\} \subset C_4$ is an invariant subgroup.

$$a \quad H' = \{\cancel{a} a e a^3, a a^2 a^3\} = \{e, a^2\}$$

$$a^2 \quad H' = \{a^2 e a^2, a^2 a^2 a^2\} = \{e, a^2\}$$

$$a^3 \quad H' = \{a^3 e a, a^3 a^2 a\} = \{e, a^2\}$$

H is identical to all of its conjugate subgroups.

Every group has at least two invariant subgroups $\{e\}$ and the whole group G .

If non-trivial invariant subgroups exist, the full group can be simplified or factored

Def: Simple and Semi-simple Groups

A group is simple if it has no non-trivial invariant subgroups.

A group is semi-simple if it does not contain any abelian invariant subgroup.

Examples: (a) C_4 contains an abelian invariant subgroup - it is neither simple nor semi-simple
 (b) C_p with p prime is simple.

(2.7)

2.5 Cosets and Factor (Quotient) Groups

Df: Cosets $1 H = \{h_1, \dots, h_n\} \subset G$ and $p \in G$ while $p \notin H$.

$pH = \{ph_1, \dots\}$ is a left coset of H

$Hp = \{h_1p, \dots\}$ is a right coset of H .

All results for left cosets apply to right ones.

Lemma: Two left cosets of a subgroup H either coincide completely or have no elements in common.

Pf. Let pH and qH be two cosets.

Assume $\exists h_i, h_j \in H \Rightarrow ph_i = qh_j \leftarrow$ two elements in common.

then $h_i h_j^{-1} = q p^{-1} \iff q p^{-1} \in H \Rightarrow$
 $q^{-1} p \in H \Rightarrow$

$q^{-1} p H = H \Rightarrow pH = qH \Rightarrow$ The two cosets are the same.

So Given a subgroup of order n_H , the distinct cosets of H partition the full group G into disjoint-sets of n_H each.

Lagrange's Thm: The order of a finite group must be an integer multiple of the order of any of its subgroups.

The cosets (left and right) of an invariant subgroup H are equal.

Recall $p H p^{-1} = H \Rightarrow$

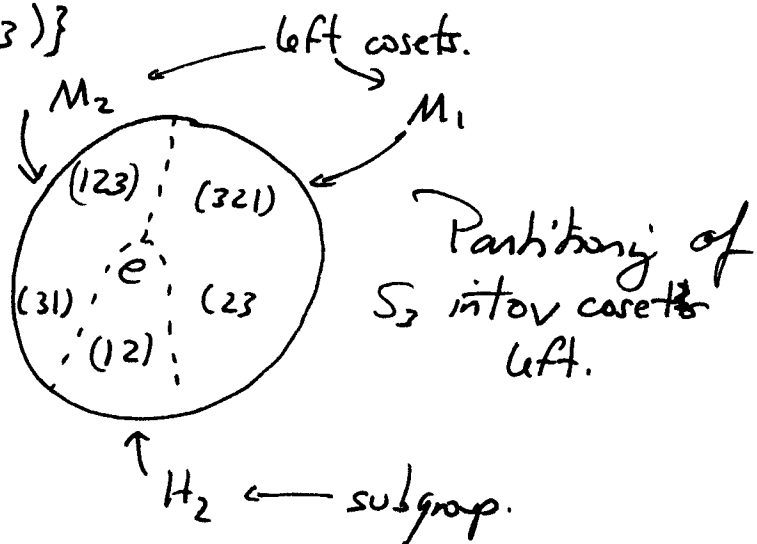
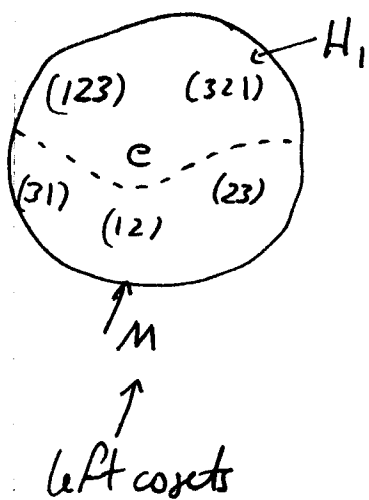
$p H = H p$. ✓

Examples w/ S_3

$H_1 \subset S_3 \quad \{e, (123), (321)\} \xrightarrow{\text{one left coset}} M = \{(12), (23), (31)\}$

e.g. $(12)(123) = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix} = (23)$ etc.

$H_2 \subset S_3 \quad \{e, (12)\}$ has two left cosets
 $M_1 = \{(23), (321)\}$
 $M_2 = \{(31), (123)\}$



(2.9)

Consider the cosets of an invariant subgroup as elements of a new group.

$$(pH) \cdot (qH) = \text{coset } (pq)H$$

why? $ph_i qh_j = pqh_k$ because we need to show that there is $h_k \in H$ so that

$$h_k = (q^{-1}h_i q)h_j$$

↑
this is in H since H is an invariant subgroup.

- (i) $H = eH$ is the identity element.
- (ii) $p^{-1}H = (pH)^{-1}$
- (iii) $pH (qH \cdot rH) = (pqr)H$

Thm: If H is an invariant subgroup of G , the set of cosets endowed w/ the multiplication law $pH \cdot qH = pqH$ forms a group. — the factor group or quotient group G/H . It is of order $|G|/|H|$.

Example: $C_4 = \{e, a, a^2, a^3\}$ has an invariant subgroup $H = \{e, a^2\}$ with the cosets

$$M = \{a, a^3\} \text{ and } H.$$

$$\text{Now } MH = M = HM \text{ and } MM = H$$

2.10

$$\text{So, } C_4/H \cong C_2$$

Another example: this time we look at the permutation group or symmetric group. S_3

$H = \{e, (123), (321)\}$ is an invariant subgroup.
with two cosets:

$$H \text{ and } M = \{(12), (13), (23)\}$$

$$HM = H(ij)H = (ij)H = M$$

check.

$$(12)(123) = \begin{pmatrix} 123 \\ 213 \end{pmatrix} \begin{pmatrix} 123 \\ 231 \end{pmatrix} = \begin{pmatrix} 123 \\ 132 \end{pmatrix} = (23)$$

$$\text{So } S_3/H \cong C_2$$

2.6 Homomorphisms

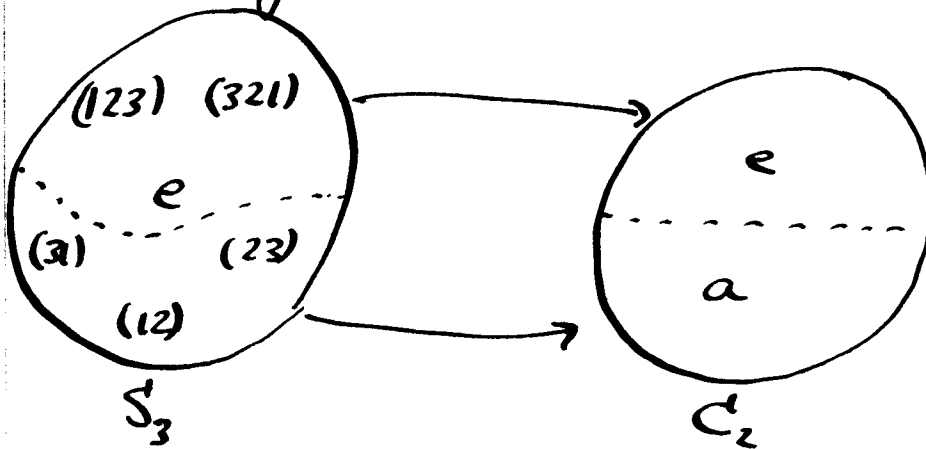
Def: A homomorphism from a group G to another group G' is a mapping which preserves the group multiplication rule.

$$g_i \in G \text{ and } g'_i \in G'$$

$$g_2 = g_1 g_2 \rightarrow g'_1 g'_2 = g'_3$$

(2.11)

The mapping from S_3 to C_2 is a homomorphism



any three cycle times e or a three cycle is another three cycle. Any two cycle times a two cycle is e . and any two ~~two~~ cycle times a three cycle is another two cycle.

$$\begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} = (12)$$

$$(123) \cdot (23) = (12)$$

This reproduces the multiplication table of $C_2 = \{e, a, a^2 = e\}$.

Thm 2.5 ~~Let~~ Let f be a homomorphism from G to G' . $K =$ set of all elements mapped to the identity in G' .

$$K = \{a \in G; a \xrightarrow{f} e' \in G'\}$$

Then K forms an invariant subgroup of G . And,

$G/K \cong G'$ First show that K is a group (2.12)

Pf: If $a, b \in K$ then $ab \xrightarrow{f} e' \cdot e' = e' \Rightarrow ab \in K$

Since we have a homomorphism $e \xrightarrow{f} e'$

Thus $e \in K$ and if $a \in K$ then $a^{-1} \xrightarrow{f} e'$ if $a \xrightarrow{f} e'$

$a^{-1} \xrightarrow{f} e'^{-1} = e'$ so K is a subgroup.

Now we need to show that K is an invariant subgroup.

$a \in K$ and $g \in G$ Then

$$gag^{-1} \xrightarrow{f} g'e'g'^{-1} = g'g'^{-1} = e'$$

$\Rightarrow gag^{-1} \in K$ for all $g \in G \Rightarrow K$ is an invariant subgroup.

Now we look at the factor group G/K . Elements of G/K are cosets pK

Consider the mapping $pK \xrightarrow{f} p' \in G'$ where $p \xrightarrow{f} p'$

The mapping f is one-to-one. To check this we note:

$$\text{If } f(pK) = f(qK) \text{ then } f(q^{-1}pK) =$$

$$f(q^{-1}KpK) = f(q^{-1}K)f(pK)$$

← Needs to think about why this is true.

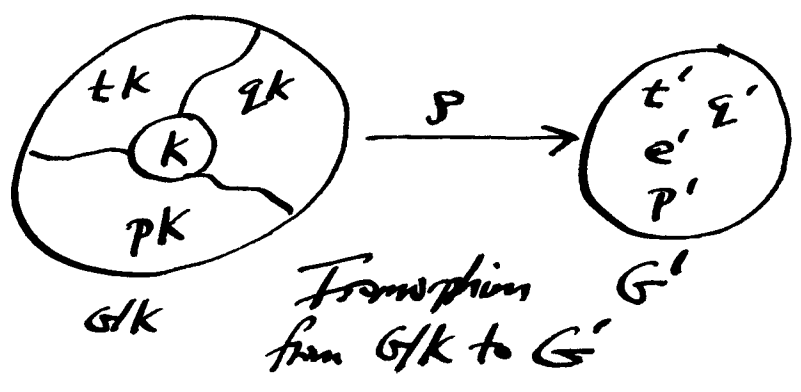
Why is $f(pk)g(qk) = f(pqk)$?

Ans. $pk \xrightarrow{f} p'$ if $p \xrightarrow{f} p'$. So any element of the coset pk goes to p' under $f \Rightarrow f$ maps the coset pk to p' .

$f(pk)g(qk) = p'q'$ and $(pq)' = p'q'$ since f is a homomorphism so we have just proven the point. means the inverse of $f(qk) \in G'$

Then $f(q^{-1}pk) = f^{-1}(qk)f(pk) = e' \Rightarrow$ either $q^{-1}pk = k$ or $qk = pk \therefore$ The mapping is one-to-one.

Since group multiplication is reversed f is an isomorphism. $\Rightarrow G/K \cong G'$.



Def: Direct Product Group

Let $H_1, H_2 \subseteq G$ with the properties

(i) elements of H_1 commute w/ elements of H_2
 $h_1 h_2 = h_2 h_1 \quad \forall h_1 \in H_1, h_2 \in H_2$.

(ii) any element $g \in G$ can be written uniquely as
 $g = h_1 h_2, h_1 \in H_1, h_2 \in H_2$

Then $G = H_1 \otimes H_2$

example: $C_6 = \{e = a^6, a, a^2, \dots\}$

subgroups $H_1 = \{e, a^3\}$ and $H_2 = \{e, a^2, a^4\}$

$H_1 \cong C_2 \quad H_2 \cong C_3 \Rightarrow$

$$C_6 = C_2 \otimes C_3$$

If $G = H_1 \otimes H_2$ then both H_1 and H_2 must be invariant subgroups of G .

Why? if $g = h_1 h_2 \in G$ $h_1, a_1 \in H_1$
 $h_2 \in H_2$

then $g a_1 g^{-1} = \underbrace{h_1 h_2 a_1 h_2^{-1} h_1^{-1}}_{\text{commute}} = h_1 a_1 h_1^{-1} \in H_1$ for all g and a_1

so H_1 is an invariant subgroup.

Now we can form the quotient group G/H_1 or G/H_2 .
 we want to prove that $G/H_1 \cong H_2$ and $G/H_2 \cong H_1$

2.15

Consider the mapping $pH_1 \xrightarrow{\varphi} h_2$ where $p = h_1 h_2$

$$p \in G$$

$$\Rightarrow p = h_1 h_2 \text{ for some } h_1 \in H_1, h_2 \in H_2$$

$$pH_1 = p h_1 h_2 h_1' = p h_1'' h_2$$

Need to show that φ is a 1-to-1 homomorphism.

1-to-1 say $\varphi(pH_1) = \varphi(qH_1)$ then:

$$p = h_1 h_2 \text{ and } q = h_1' h_2' \text{ but}$$

$$\varphi(pH_1) = \varphi(h_2 h_1 H_1) = \varphi(h_2 H_1) = h_2$$

$$\varphi(qH_1) = \varphi(h_2' h_1' H_1) = \varphi(h_2' H_1) = h_2'$$

$$\Rightarrow h_2 = h_2' \text{ so}$$

$$pH_1 = h_1 h_2 H_1 = h_2 H_1$$

$$qH_1 = h_1' h_2 H_1 = h_2 H_1$$

$\Rightarrow pH_1 = qH_1$ ✓ one-to-one mapping.

clearly preserve the group multiplication since

$$\varphi(pH_1) \varphi(qH_1) = \varphi(pqH_1) \text{ then } pq = h_2 h_1$$

and

$$p = h_1^{(p)} h_2^{(p)} \quad q = h_1^{(q)} h_2^{(q)} \text{ so } pq =$$

$$pq = h_1^{(p)} h_1^{(q)} h_2^{(p)} h_2^{(q)} \text{ so}$$

$$\varphi(pqH_1) = h_2^{(p)} h_2^{(q)} \text{ and } \varphi(pH_1) \varphi(qH_1) = h_2^{(p)} h_2^{(q)} \checkmark$$

Representations of Groups:

homomorphism U from a group G to linear operators on a vector space $V \Rightarrow U(G)$ forms a representation of the group G of dimension $\dim(V)$.

$$g \in G \xrightarrow{U} U(g) \text{ and if } g_1 g_2 = g_3 \text{ then}$$

$$U(g_1) U(g_2) = U(g_3)$$

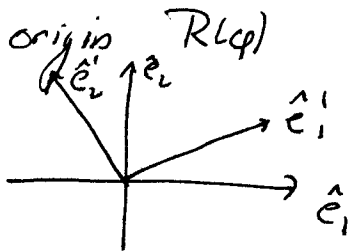
Finite Dimensional Vector space spanned by $\{\hat{e}_1, \dots, \hat{e}_n\}$ we can define $n \times n$ matrices representing the operators $U(g)$ called $D(g)$ such that

$$U(g) |\hat{e}_i\rangle = |\hat{e}_j\rangle D_{ij}^j(g) \quad \begin{matrix} \text{row} \\ \downarrow \\ D_{ij}^j(g) \\ \uparrow \\ \text{column} \end{matrix}$$

$$\begin{aligned} \text{Then } U(g_1) U(g_2) |\hat{e}_i\rangle &= U(g_1) |\hat{e}_j\rangle D_{ij}^j(g_2) \\ &= |\hat{e}_k\rangle D_{kj}^j(g_1) D_{ij}^j(g_2) \end{aligned}$$

$$\text{so } D_{ij}^j(g_1 g_2) = D_{kj}^j(g_1) D_{ij}^j(g_2)$$

Example $G =$ group of rotations in the plane about the origin $R(\varphi) \quad 0 \leq \varphi \leq 2\pi$



$$\hat{e}_1' = \cos\varphi \hat{e}_1 + \sin\varphi \hat{e}_2$$

$$\hat{e}_2' = -\sin\varphi \hat{e}_1 + \cos\varphi \hat{e}_2$$

$$U(\varphi) |\hat{e}_i\rangle = |\hat{e}'_i\rangle \text{ etc.}$$

Note $\vec{x}' = D(\varphi) \cdot \vec{x}$ or $x'^j = D(\varphi)^j_i x^i$ where we determine D from its action on the unit vectors $|\hat{e}_k\rangle$:

$$x'^j |\hat{e}'_j\rangle = D(\varphi)^j_i x^i |\hat{e}_j\rangle \text{ and}$$

$$\vec{x}'^l = [U(\varphi) \vec{x}]^l \Rightarrow x^k D^l_k |\hat{e}_k\rangle \text{ so}$$

~~$U(\varphi) |\hat{e}_p\rangle = |\hat{e}'_p\rangle D^k_p$~~

$\underbrace{\hspace{10em}}_{\substack{\text{summing on the rows!} \\ \text{not on the columns.}}}$

Example 2: $V_f =$ complex-valued linear homogeneous functions of real variables (x, y) .

$$f(x, y) = ax + by \quad f \xrightarrow{g \in G} f'(x', x'') \equiv f(x', x'')$$

where $\vec{x}' = U(g^{-1})\vec{x}$

Note if $f \xrightarrow{g'} f'$ $f(x) = f[U(g')^{-1}\vec{x}]$
 $f' \xrightarrow{g''} f''$ $f''(x) = f'[U(g'')^{-1}\vec{x}]$

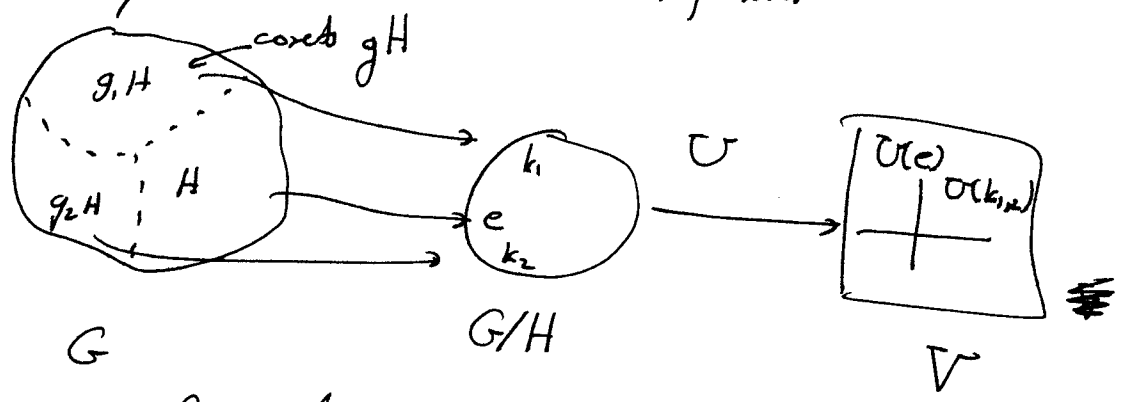
so $f''(x) = f[U(g'')^{-1}U(g')^{-1}\vec{x}] = f[U(g''g')^{-1}\vec{x}]$
so ~~$U(g''g')$~~ the action of $g''g'$ is the same as

the action of g' followed by the action g'' i.e.

$$f \xrightarrow{g = g''g'} f'' \text{ where } f''(x) = f[U(g)^{-1}x]$$

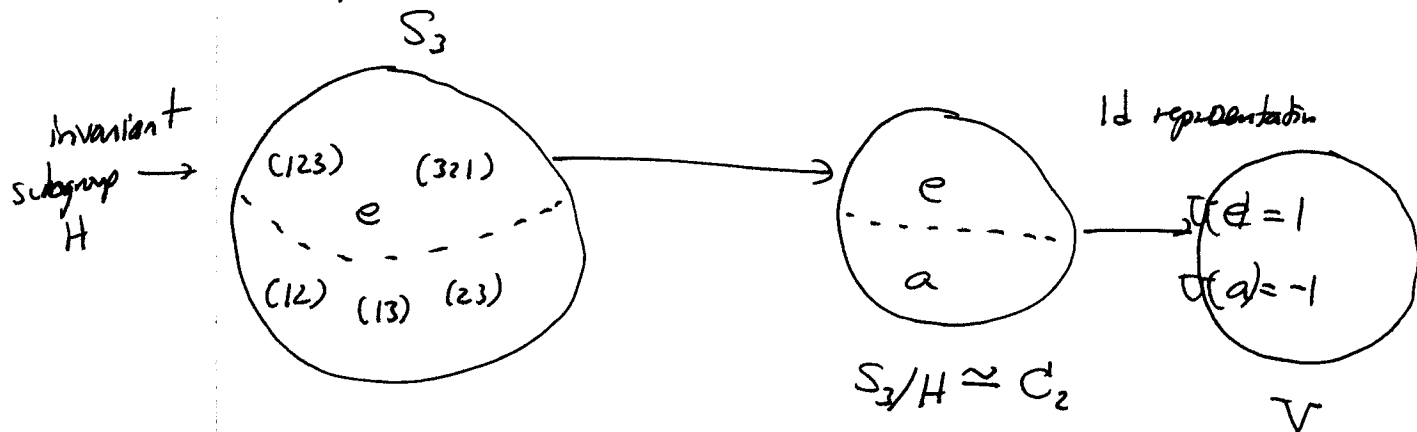
Thm 3.1 (i) If G has a non-trivial invariant subgroup H then any representation of the factor group $K = G/H$ is also a representation of G . This representation is degenerate
 (ii) If $U(G)$ is a degenerate representation of G , then G has at least one invariant subgroup $H \ni U(G)$ defines a faithful representation of G/H .

Pf: The mapping $g \in G \rightarrow k = gH \in K$ followed by $k \rightarrow U(k)$ on V is a homomorphism $G \rightarrow U(k)$
 If H is a non-trivial invariant subgroup, then $g \rightarrow k$ is many to one \Rightarrow Not a faithful representation.



2nd part follows from Thm 2.5.

Example:



This induces a non-faithful 1d representation on S_3 :

$$\begin{aligned} \{ e, (123), (321) \} &\xrightarrow{U'} 1 \\ \{ (12), (13), (23) \} &\xrightarrow{U'} -1 \end{aligned}$$

Note that this picks out even and odd (-1) permutations of the numbers 123.

3.2 Irreducible, Inequivalent Representations

Def: Two representations related by a similarity transformation are equivalent

$$U'(G) = S U(G) S^{-1}$$

$\iff U'$ and U are equivalent.

Def: Character of a representation

$$\chi(g) = \text{Tr } U(g)$$

\implies All group elements in a conjugate class ~~are equivalent~~ have the same character.

$$a = p g p^{-1} \Rightarrow$$

$$a = \cancel{p g p^{-1}} p g p^{-1}$$

(3.5)

$$\Rightarrow U(a) = U(p)U(g)U(p)^{-1} \Rightarrow$$

$$\text{Tr } U(a) = \text{Tr } U(g) \quad \checkmark$$

Note also that the trace (or character) is invariant under similarity transformations. So, χ labels conjugate classes only. \leftarrow I mean uniquely, in a representation.

Another ~~redundancy~~ \rightarrow Direct Sum Representations

Let $U(G)$ be a representation on V_n and for some choice of basis

$$D(g) = \begin{pmatrix} D_1(g) & 0 \\ 0 & D_2(g) \end{pmatrix} \quad \text{for all } g \in G$$

Then $D(g)$ does not contain any new information not already in $D_1(g)$ and $D_2(g)$.

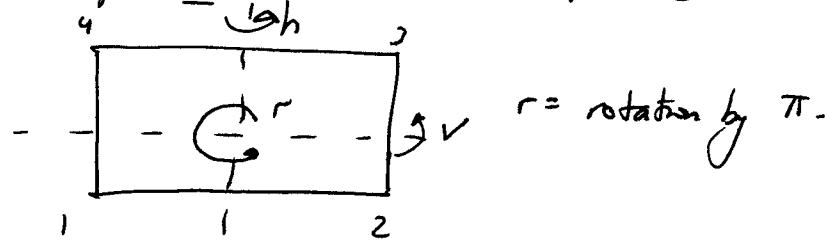
Def: Invariant subspace

subspace V_1 of V which has the property that for all $|x\rangle$ in V_1 $U(g)|x\rangle \in V_1$ for all $g \in G$.

Def: Irreducible Representation:

A rep $U(G)$ on V is irreducible if there is ~~no~~ non-trivial invariant subspace in V w.r.t $U(G)$

Examples: A Dihedral Group $D_2 = \{e, h, v, r\}$



$r = \text{rotation by } \pi$.

$$D(e) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad D(h) = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \quad D(v) = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$D(r) = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$$

Note that both \hat{e}_1 and \hat{e}_2 make invariant subspaces of $V = \hat{e}_1, \hat{e}_2$ - spanned by ...

There is a one-dimensional rep of $\{-1, 1\}$ on each axis that is irreducible.

B_{11} V spanned by \hat{e}_1, \hat{e}_2 but the group $R(2)$ the vectors

$$\hat{e}_{\pm} = \frac{1}{\sqrt{2}} (\mp \hat{e}_1 + i \hat{e}_2)$$

form each a 1-d invariant subspace

$$U(\varphi) \hat{e}_{\pm} = \hat{e}_{\pm} e^{\mp i\varphi}$$

in the new basis

$$D(\varphi) = \begin{pmatrix} e^{-i\varphi} & 0 \\ 0 & e^{i\varphi} \end{pmatrix}$$

Unitary Representations:

Thm: If a unitary representation is reducible, then it is also decomposable (i.e. fully reducible)

(3.7)

Pf: let $\rho(G)$ be a reducible rep of G on the inner product space V

V_1 is an invariant subspace [$\dim(V_1) = n_1$] wrt $\rho(G)$

Take an orthonormal basis $\{\hat{e}_i\}_{i=1, \dots, n}$ for V

$\exists \quad i=1, \dots, n_1$ spans V_1 and $i=n_1+1, \dots, n$ spans V_2 , the orthogonal complement.

We need to show that V_2 is also invariant wrt $\rho(G)$

$$|\hat{e}_i(g)\rangle = \rho(g)|\hat{e}_i\rangle \in V_1 \quad \text{for } i=1, \dots, n_1$$

Since $\rho(G)$ is unitary $\langle \hat{e}_j^i(g) | \hat{e}_i(g) \rangle = 0$ for all $j=n_1+1, \dots, n$ and all $i=1, \dots, n_1$

Thus any vector \bar{x} in V_2 remains there under the action $\rho(G)$. We say $V = V_1 \oplus V_2$.

Thm 3.3 Every representation of a finite group on an inner product space is equivalent to a unitary rep.

Need to find S so that $S \rho(G) S^{-1} = \rho(G)$
↑ unitary.

for all $g \in G$.

S can be chosen to satisfy

$$(x, y) \equiv \langle Sx | Sy \rangle = \sum_g \langle D(g)x | D(g)y \rangle$$

(3.8)

Note: 1 (x, y) satisfies the axioms of a scalar product.

$$(x, y) = (y, x)^*$$

$$(x, x) \geq 0 \text{ and } = 0 \text{ iff } x = 0.$$

2 S is a transformation from a basis orthonormal wrt $\langle | \rangle$ to one orthonormal wrt $(,)$.

Schur's Lemmas

1. Let $\rho(G)$ be an irreducible rep of G on V and

let A be an operator on V

$$\text{if } [A, \rho(g)] = 0 \quad \forall g \in G \quad \text{then}$$

$$A = \lambda E, \text{ where } \lambda = \text{a number}$$

\uparrow Identity operator.

\Rightarrow Irreducible reps of an abelian group have dimension 1.

Why? Because $\rho(g')$ commutes w/ all $\rho(g)$, $g \in G$

$$\Rightarrow \rho(g') = \lambda_{g'} E.$$

Pf of Schur's First Lemma:

Take $\rho(G)$ to be unitary and make A Hermitian

if A is not comm with ρ will

$$A_+ = \frac{A + A^\dagger}{2} \quad A_- = \frac{A - A^\dagger}{2i}$$

Take the basis of V to be eigenvectors of A .

to label vectors in degenerate subspaces of A .

* $|u_{\alpha,i}\rangle$ \leftarrow may be chosen to be orthonormal. (3.9)

$$A|u_{\alpha,i}\rangle = |u_{\alpha,i}\rangle \lambda_i$$

Note: for any i $\{|u_{\alpha,i}\rangle; \alpha=1,2,\dots\} = V^i$ are invariant subspaces w.r.t $U(G)$.

$$A U(g)|u_{\alpha,i}\rangle = U(g) A |u_{\alpha,i}\rangle = \lambda_i U(g)|u_{\alpha,i}\rangle$$

$$\text{so } U(g)|u_{\alpha,i}\rangle \in V^i \checkmark$$

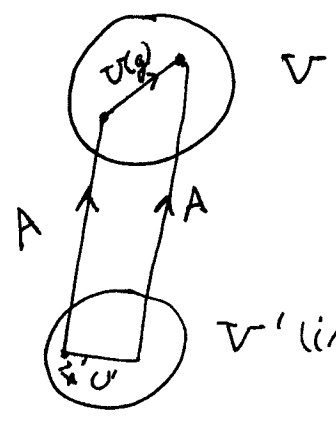
But $U(G)$ is irreducible on $V \Rightarrow V^i$ must be V
 $\Rightarrow A$ has only one eigenvalue $\Rightarrow A = \lambda E$.

Schur's 2nd Lemma:

Let $U(G)$ and $U'(G)$ be two irreducible reps of G on V and V' respectively.

Let A be linear transformation from V' to V such that
 $AU'(g) = U(g)A$ for all $g \in G$.

Then either $A = 0$ or
 V is isomorphic to V' and $U(G)$ is equivalent to $U'(G)$.



$R = \text{the range of } A$
 $R = \{ \bar{x} \in V \mid \bar{x} = A\bar{x}', \bar{x}' \in V' \}$

(i) R is an invariant subspace of V wrt $U(G)$

$$\iff | \bar{x} \rangle \in V \quad U(g)| \bar{x} \rangle = U(g)A| x' \rangle = AU'(g)| x' \rangle$$

$$= A| U'(g)x' \rangle \in R \text{ for all } g \in G.$$

If $U(G)$ is an irreducible representation either $R=0$ or $R=V \Rightarrow$ In the first case $A=0$. ~~In the second case~~

(ii) let $N' \subset V'$ be the null space of A .
 $N' = \{ | x' \rangle \in V' \mid A| x' \rangle = 0 \}$

N' is ~~an~~ an invariant subspace of V' wrt $U'(G)$

$$\text{if } | x' \rangle \in N' \text{ then } AU'(g)| x' \rangle = U(g)A| x' \rangle = U(g)| 0 \rangle = 0$$

Since $U'(G)$ is irreducible either $N' = V'$ (hence $A=0$) or $N' = 0$ If the latter

$$A| x' \rangle = A| y' \rangle \Rightarrow | x' \rangle = | y' \rangle \text{ i.e. } A \text{ is}$$

a 1-to-1 mapping.

Thus A is an isomorphism from V' to V^* where
 $U(G) = AU'(G)A^{-1}$ or $A=0$. ✓

(3.11)

Orthonormality and Completeness Relations of Irreducible Representations of Matrices.

$n_G =$ order of group G .

$D^\mu(g) =$ matrix corresponding to $g \in G$ in the μ -representation w/ an orthonormal basis

$n_\mu =$ dimension of the μ -representation.

$n_i =$ # elements in class Z_i w/ character χ_i^μ

$n_c =$ # classes in G

Thm 3.5 Orthonormality of Irreducible Reprs.

$$\frac{n_\mu}{n_G} \sum_g D_{\mu}(g)^{+k}_i D_{\mu}(g)^{j}_e = \delta_{\mu}^{\nu} \delta_i^j \delta_e^k$$

applies to irreducible representations

for ν, l, j $D_{\nu}(g)^{j}_e \sqrt{\frac{n_\nu}{n_G}}$ can be thought of as a n_G component vector

Examples

1. C_2 d_1 identity rep. $(e, a) \xrightarrow{d_1} (1, 1)$
 another irreducible rep must be orthogonal to this one so
 d_2 $(e, a) \xrightarrow{d_2} (1, -1)$ works.

$\mu \backslash g$	e	a
1	1	1
2	1	-1

2. Dihedral Group D_2

		e	a	b	c
e		e	a	b	c
a		a	e	c	b
b		b	c	e	a
c		c	b	a	e

trivial rep: $(e, a, b, c) \xrightarrow{d_1} (1, 1, 1, 1)$

The elements $\{e, a\}$ form an invariant subgroup. $\cong C_2$
 what are the cosets? ~~$C_2 = \{e, a\}$~~

$$\begin{array}{l} \textcircled{1} \quad b\{e, a\} = \{b, c\} \\ \quad \quad c\{e, a\} = \{c, b\} \end{array} \quad \parallel \quad \begin{array}{l} \textcircled{2} \quad e\{e, a\} = \{e, a\} \\ \quad \quad a\{e, a\} = \end{array}$$

so the factor group $D_2/C_2 = \{(e, a), (b, c)\} \cong C_2$

This factor group has two inequivalent representations. From Thm 3.1 there are two induced representations of the full group D_2

$$\begin{aligned} \{e, a, b, c\} &\rightarrow \{1, 1, 1, 1\} \\ \{e, a, b, c\} &\rightarrow \{1, 1, -1, -1\} \end{aligned}$$

There are two more invariant subgroups $\{e, b\}$ and $\{e, c\}$

\Rightarrow Doing the same thing generates two more irreducible representations

$\{e, a, b, c\} \xrightarrow{d_3} \{1, -1, 1, -1\}$; $\{e, a, b, c\} \xrightarrow{d_4} \{1, -1, -1, 1\}$
 So we have the following table of inequivalent Irreducible representations of D_2 :

$\mu \backslash g$	e	a	b	c
1	1	1	1	1
2	1	1	-1	-1
3	1	-1	1	-1
4	1	-1	-1	1

Proof of Thm 3.5

X is any $n_\mu \times n_\nu$ matrix.

Define $M_X = \sum_g D_{\mu}(g)^{\dagger} X D_{\nu}(g)$; $D^{\dagger} = D^{-1}$ Recall

Then $D_{\mu}(p)^{\dagger} M_X D_{\nu}(p) = M_X$ by the rearrangement lemma.
 for any $p \in G$

By Schur's 2nd lemma $M_X = 0$ and $\mu \neq \nu$ or
 $\mu = \nu$ and $M_X = c_X E$
const \uparrow \uparrow Identity

Now choose X to be a $n_\mu \times n_\nu$ matrix with

$$\left(X_e^k \right)_j^i = \delta_j^k \delta_e^i$$

\uparrow \nwarrow
 rows over representations matrix indices

Then:

$$\begin{aligned} (M_x^k)^m_n &= \sum_g D_u^+(g)^m_i (X_x^k)^i_j D_v^-(g)^j_n \\ &= \sum_g D_u^+(g)^m_i D_v^-(g)^i_j D_x^k(g)^j_n \end{aligned}$$

the LHS is zero.

needs to be the same representation or

for $u=v$ the LHS = $c_x^k \delta_n^m$
 \uparrow
 constant.

Taking the trace of both sides:

$$\text{LHS} = n_u c_x^k$$

$$\text{RHS} = \sum_g [D_u^+(g) D_u^-(g)]^k_x = \delta_x^k n_G$$

\uparrow
 one term for each
 group element.

$$\Rightarrow c_x^k = n_G/n_u \delta_x^k \leftarrow \text{Book has } n_u/n_G ??$$

If one introduces the notation $\langle g|u, j, l \rangle = \sqrt{\frac{n_u}{n_G}} D^u(g)^j_l$

then this form takes the form:

$$\sum_g \langle u, i, k | g \rangle \langle g | v, j, l \rangle = \delta_u^v \delta_i^j \delta_x^k$$

Completeness of Irreducible Representation Matrices.

$$(i) \quad \sum_{\mu} n_{\mu}^2 = n_G$$

$$(ii) \quad \sum_{\mu, l, k} \frac{n_{\mu}}{n_G} D_{(g)k}^{\mu l} D_{(g')l}^{+k} = \delta_{gg'}$$

or

$$\sum_{\mu, l, k} \langle g | \mu, l, k \rangle \langle \mu, l, k | g' \rangle = \delta_{gg'}$$

using $\langle g | \mu, j, l \rangle = \sqrt{\frac{n_{\mu}}{n_G}} D_{(g)l}^{\mu j}$